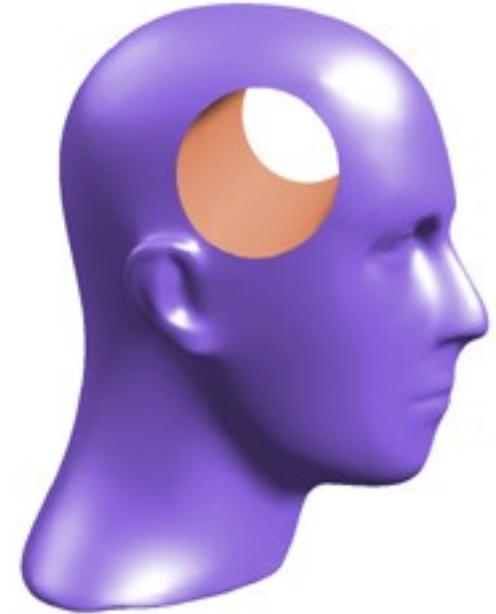


Approximate Boolean Operations on Free-form Solid

Henning Biermann
Daniel Kristjansson

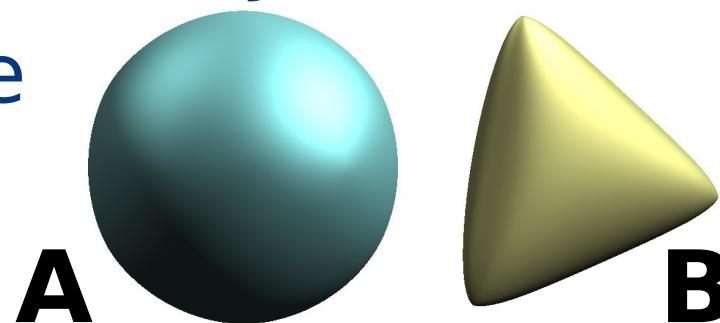


Denis Zorin
NYU

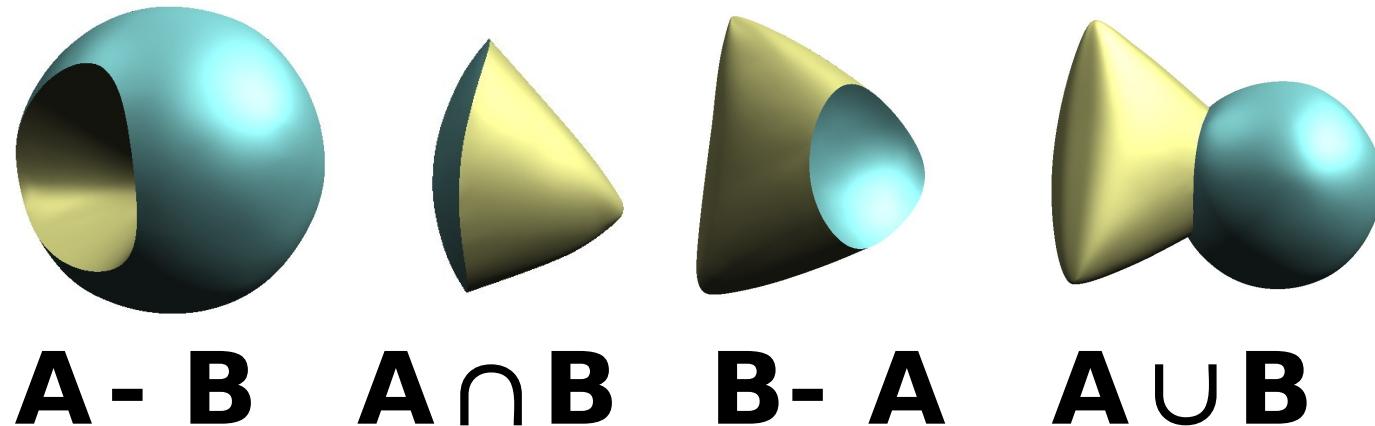
Boolean operations

Construct objects from parts

- combine



- difference, intersection, union

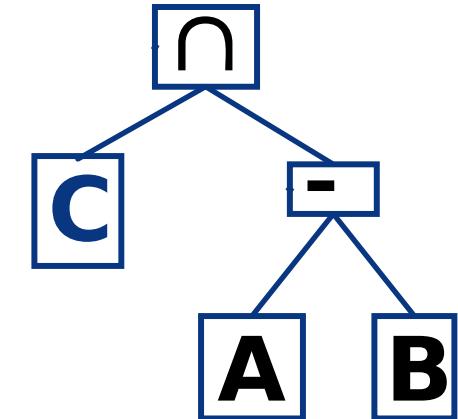


Surfaces and CSG

Constructive solid geometry

- solids: boolean expressions
combine solids naturally

not efficient for rendering,
collisions, ...



Parameteric surfaces

- efficient representation for
rendering, multiresolution, ...
- patches, subdivision, hierarchical

Approach

Approximate Boolean ops

- input: free-form solids as multires subdivision surfaces
- output: multires subdivision surface approximating the result

Want

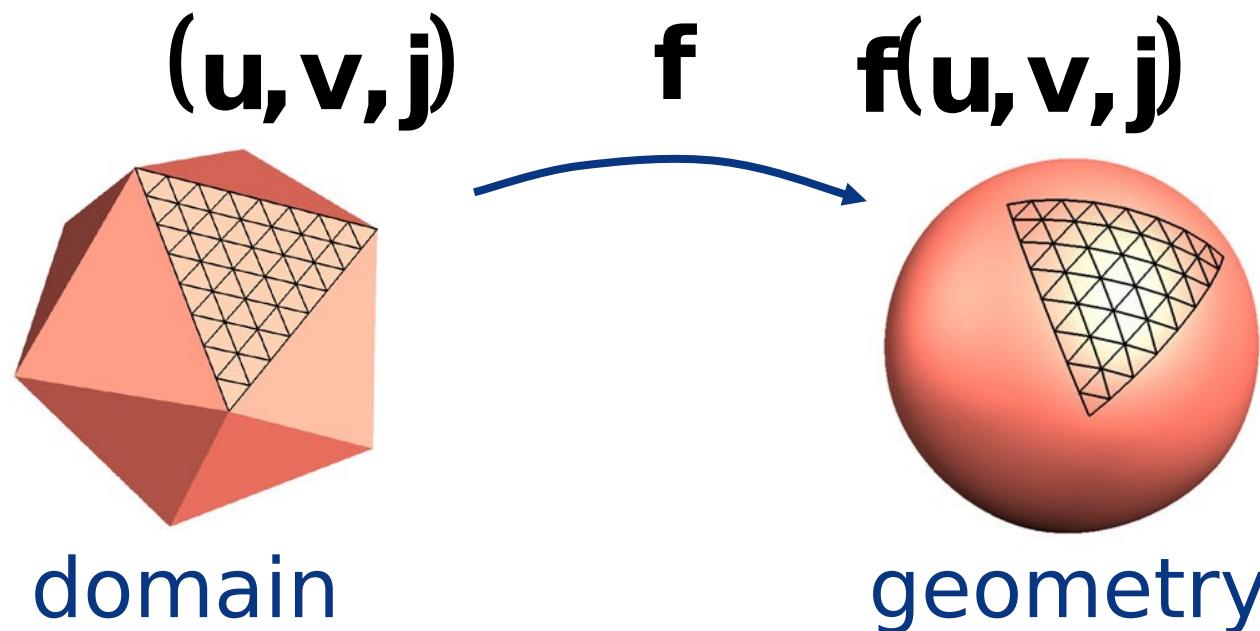
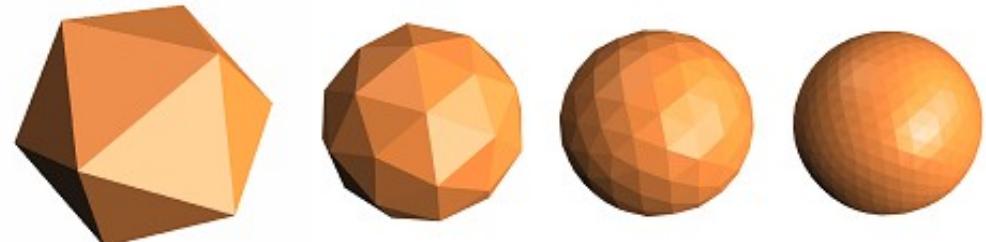
- good approximation
- coarse control meshes
- user controlled precision



Background

Multires subdivision surfaces

- recursive refinement
- parameterization



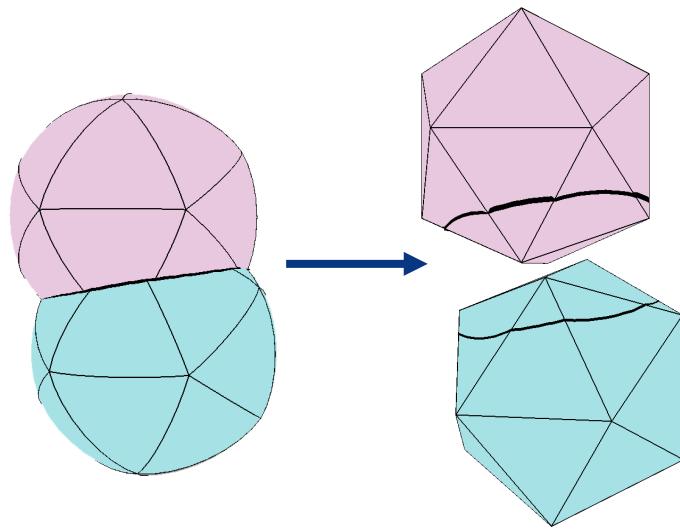
Related work

- solid modeling: too many to enumerate
- surface-surface intersection: too many...
- reparameterization: Eck et al. 95,
Krishnamurthy 96, Lee et al. 98,...
- mesh optimization: Freitag et al.
- merging control meshes: Linsen97

Overview

4 main steps

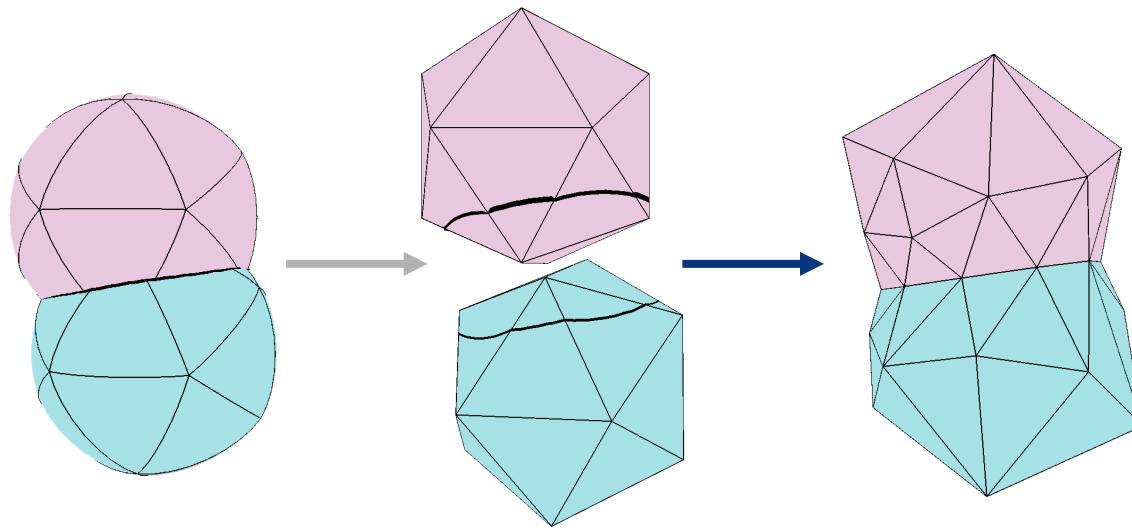
- approximate intersection
- cut and merge meshes
- parameterization
- fitting



Overview

4 main steps

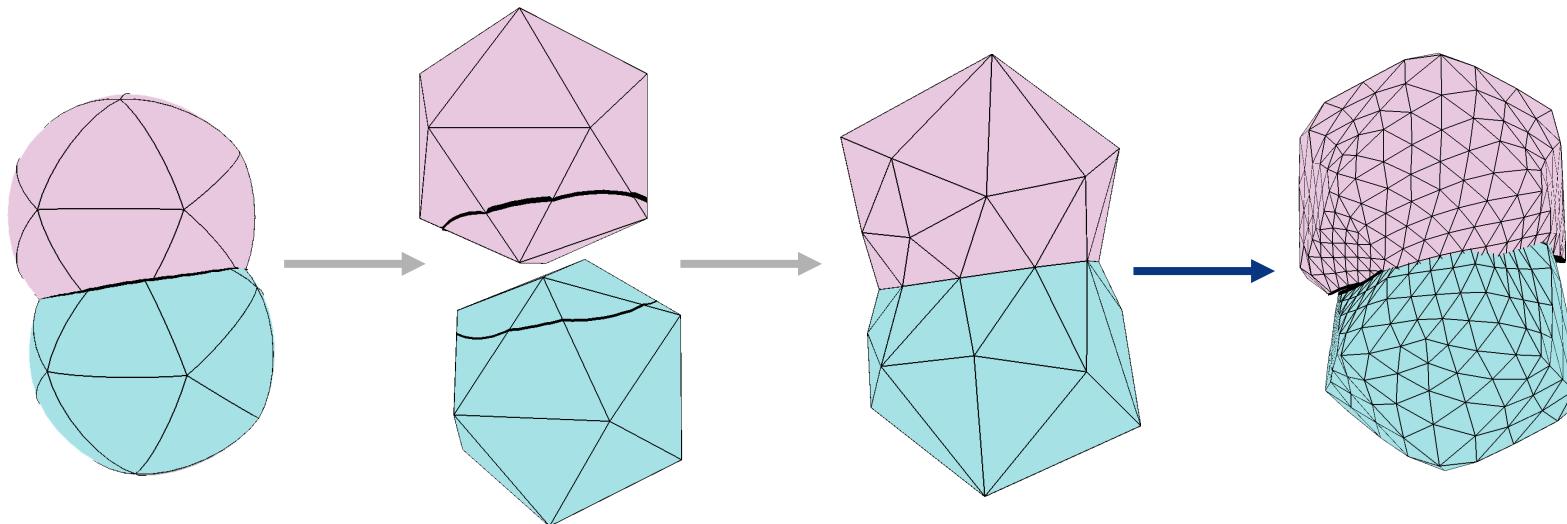
- approximate intersection
- **cut and merge meshes**
- parameterization
- fitting



Overview

4 main steps

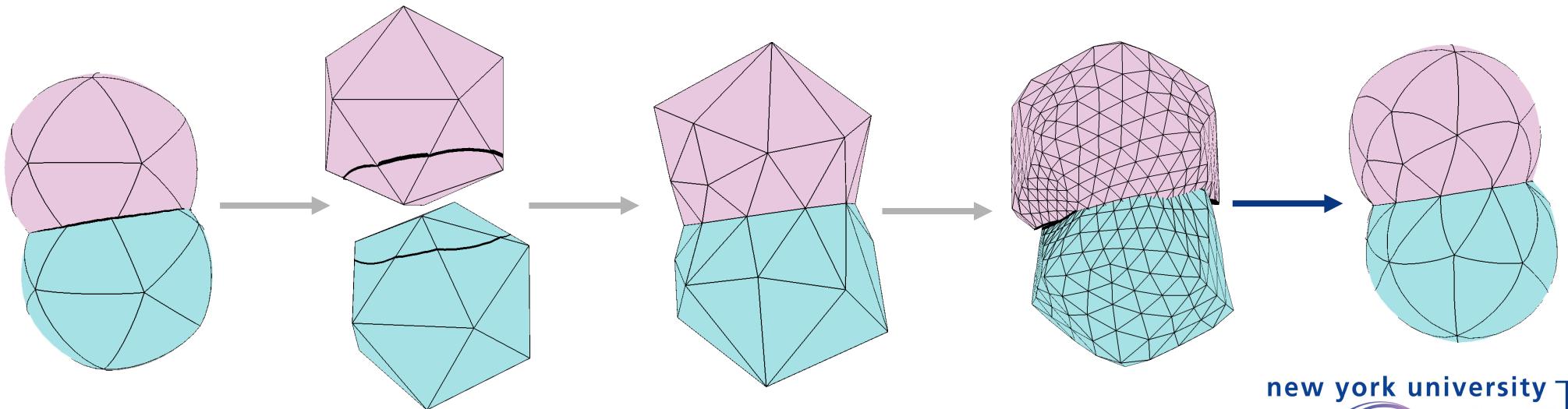
- approximate intersection
- cut and merge meshes
- parameterization
- fitting



Overview

4 main steps

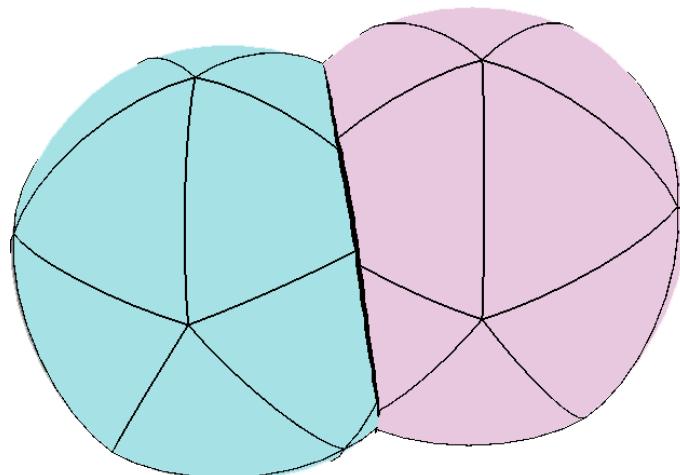
- approximate intersection
- cut and merge meshes
- parameterization
- **fitting**



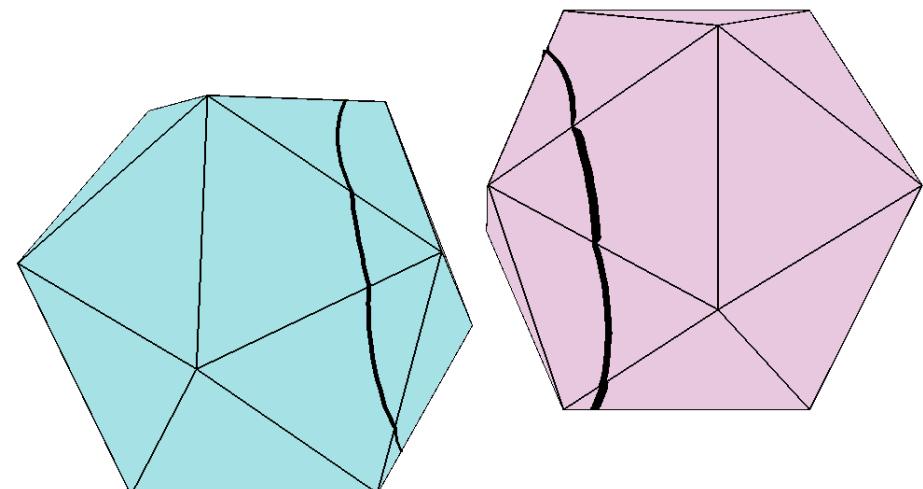
Surface intersection

Find intersection

- world-space location
- parametric location



world-space



parameter domain

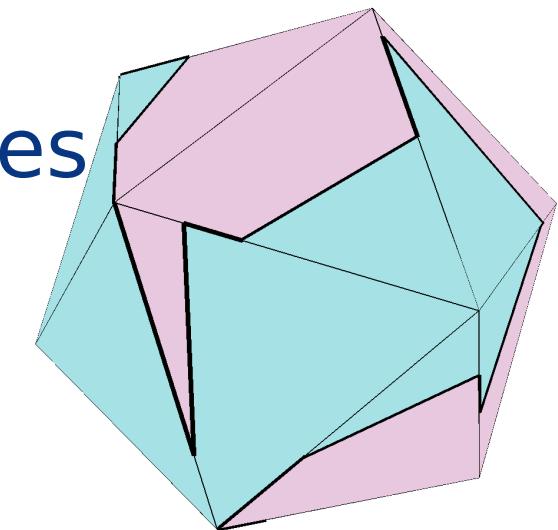
Intersections

Surface-surface intersection is difficult

- complex intersection curves
- singularities, robustness

Instead...

- robust mesh intersection
- symbolic perturbation for topological consistency

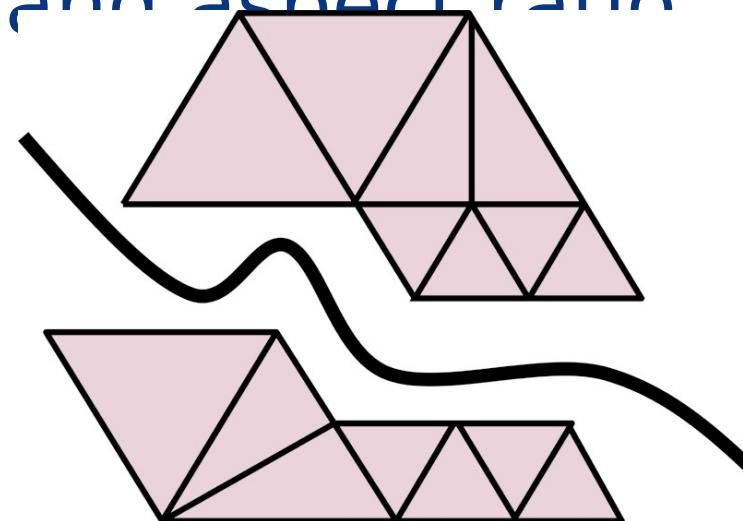
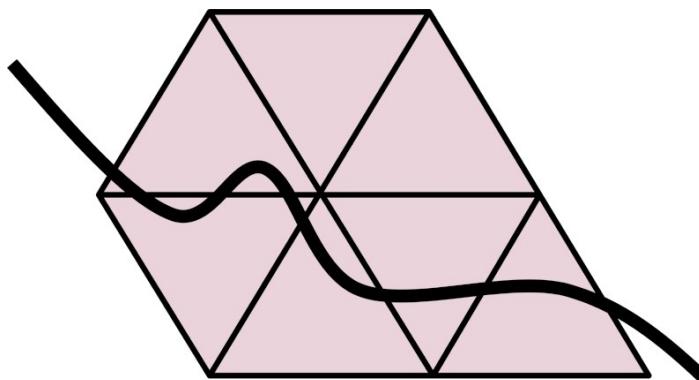


intersection of
identical solids

Cut meshes

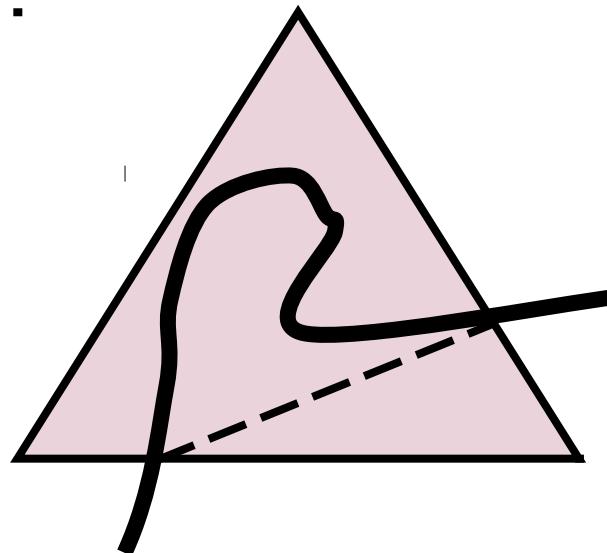
Cut meshes along straight edges

- refine to resolve curve topology
- control valence and aspect ratio

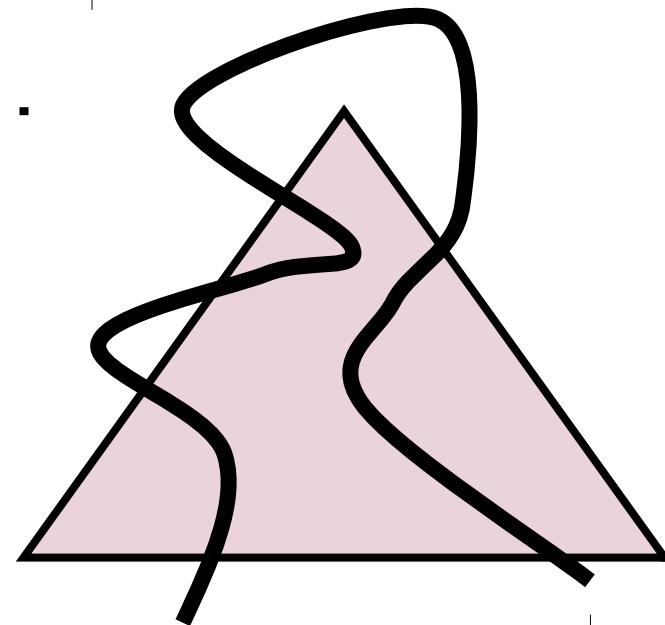


Resolve topology

Avoid refinement if possible



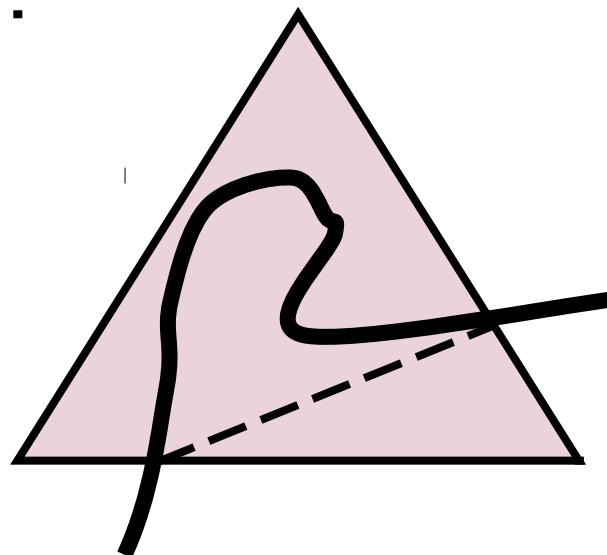
do not refine



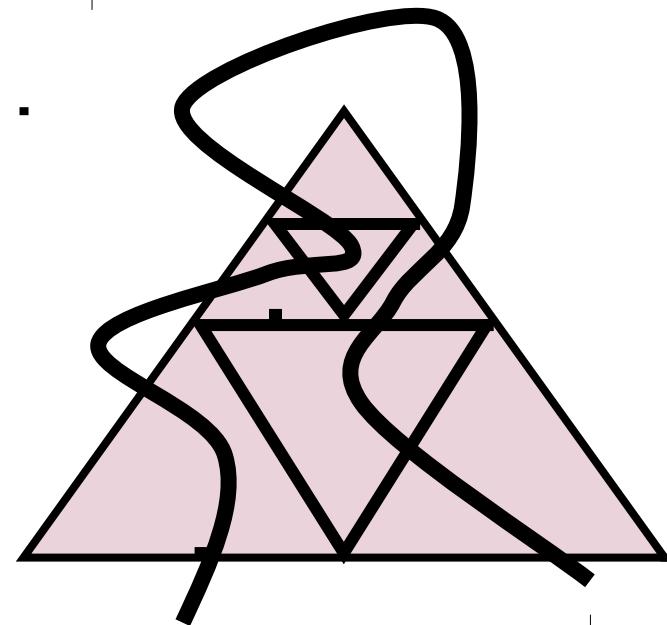
refine

Resolve topology

Avoid refinement if possible



do not refine



refine

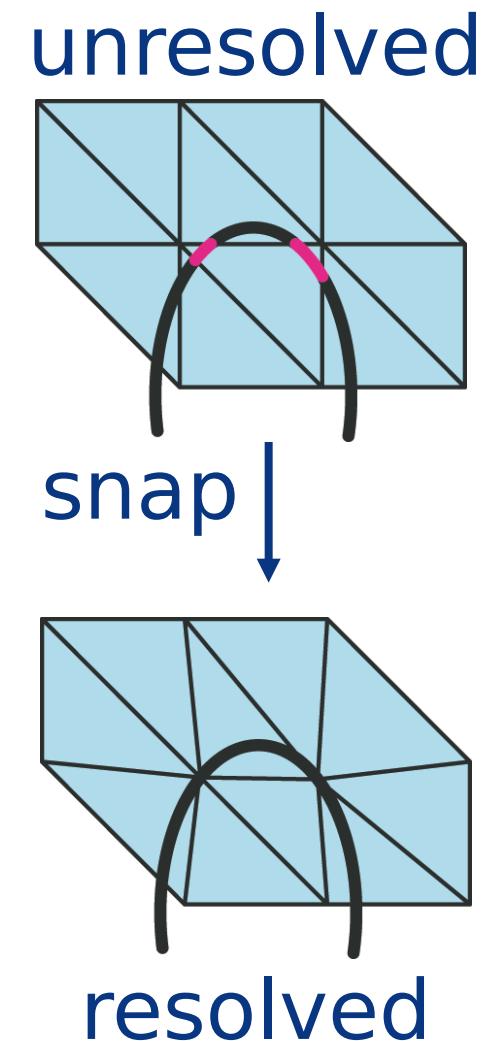
Resolve topology

Snap heuristic

- short curve segments may require many refinement steps
- snap mesh to curve to simplify intersection

Algorithm

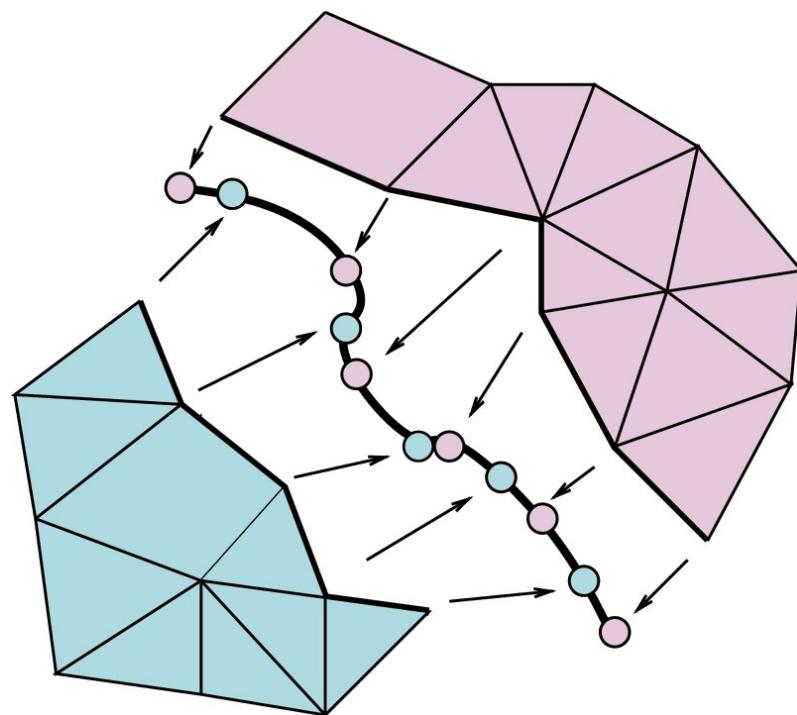
- snap mesh & refine
- repeat until topology resolved



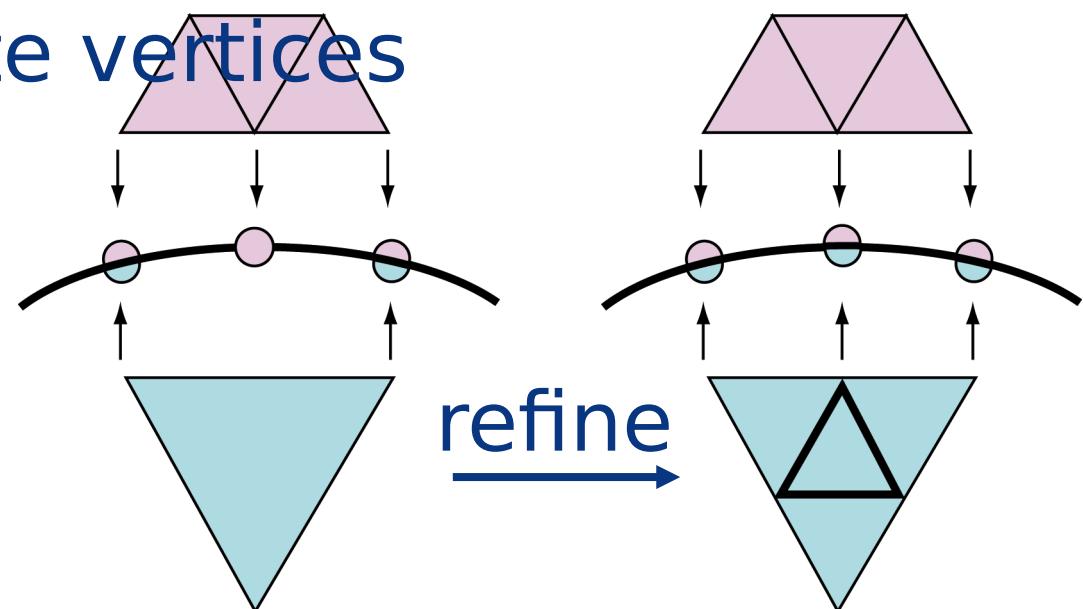
Merge meshes

Match vertices intersection
curve

- one-dimensional problem



match vertices



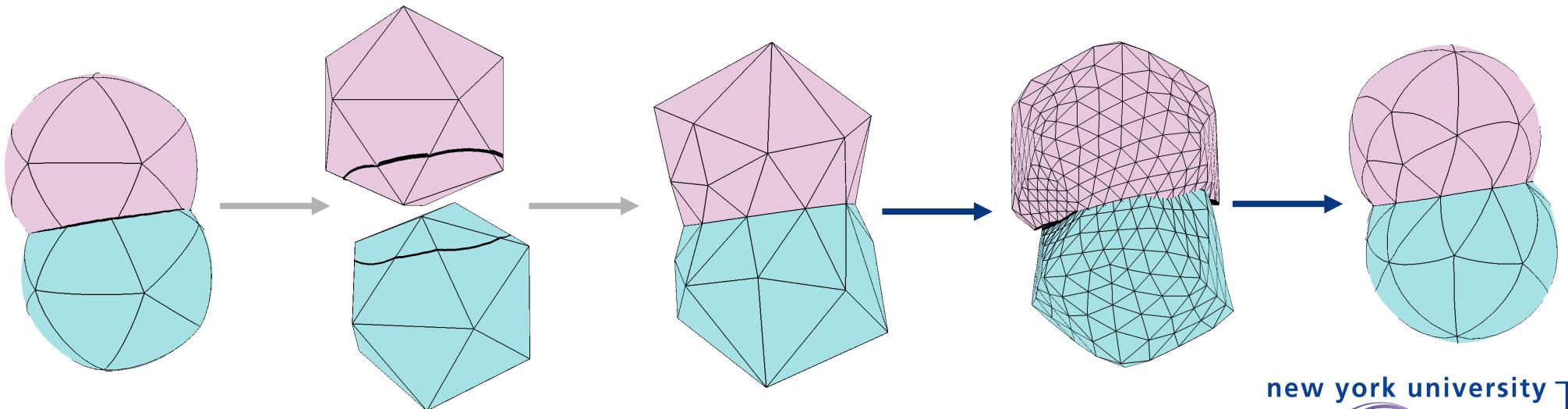
refine

Overview again

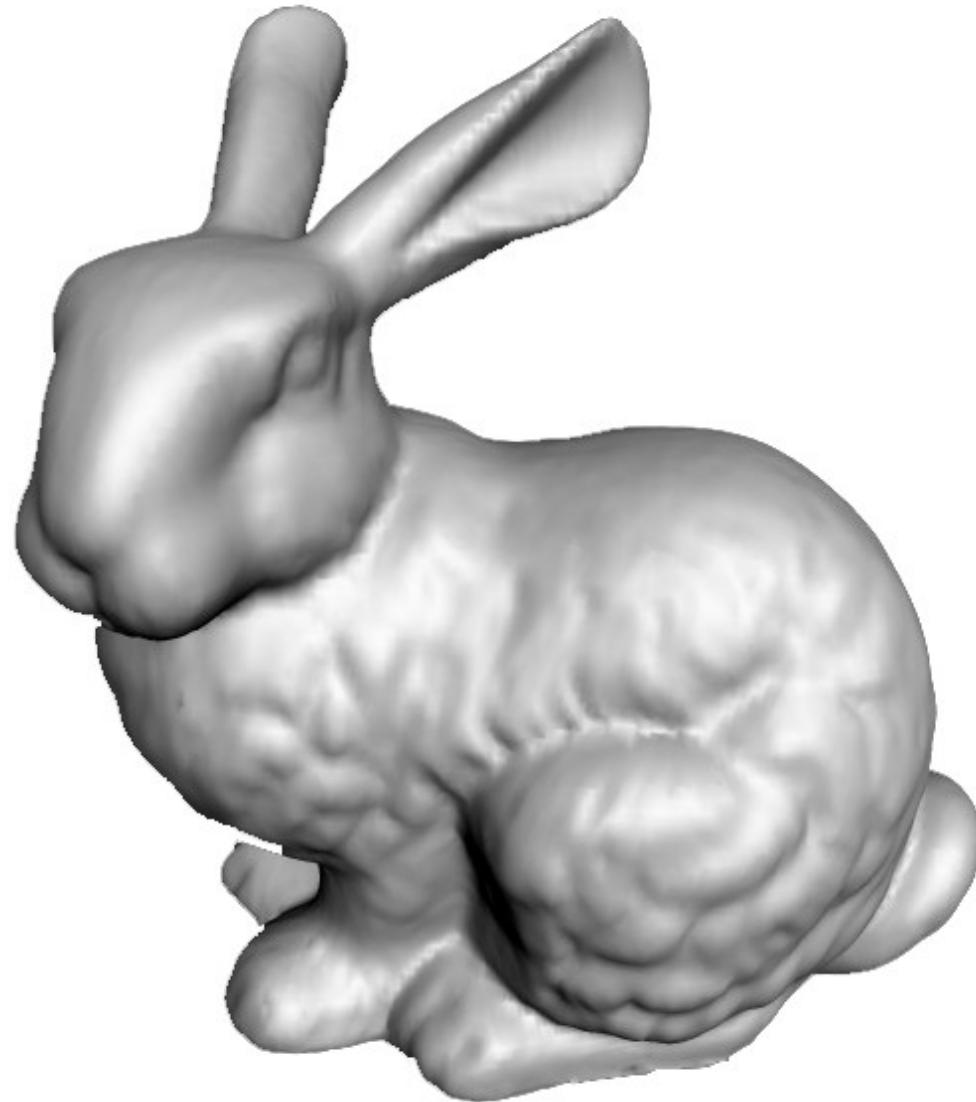
4 main steps

- approximate intersection
- cut and merge meshes
- parameterization
- fitting

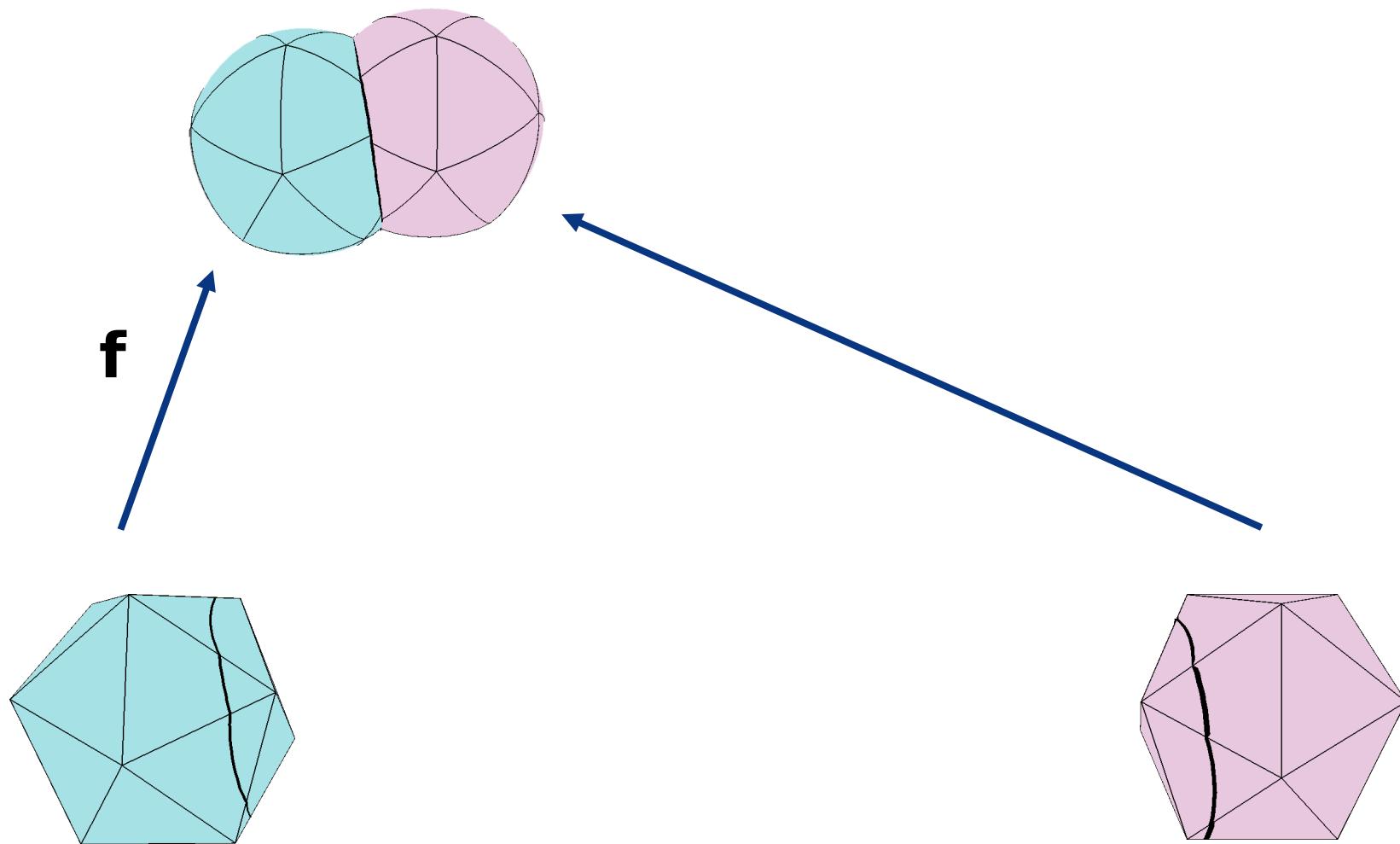
} topology
} geometry



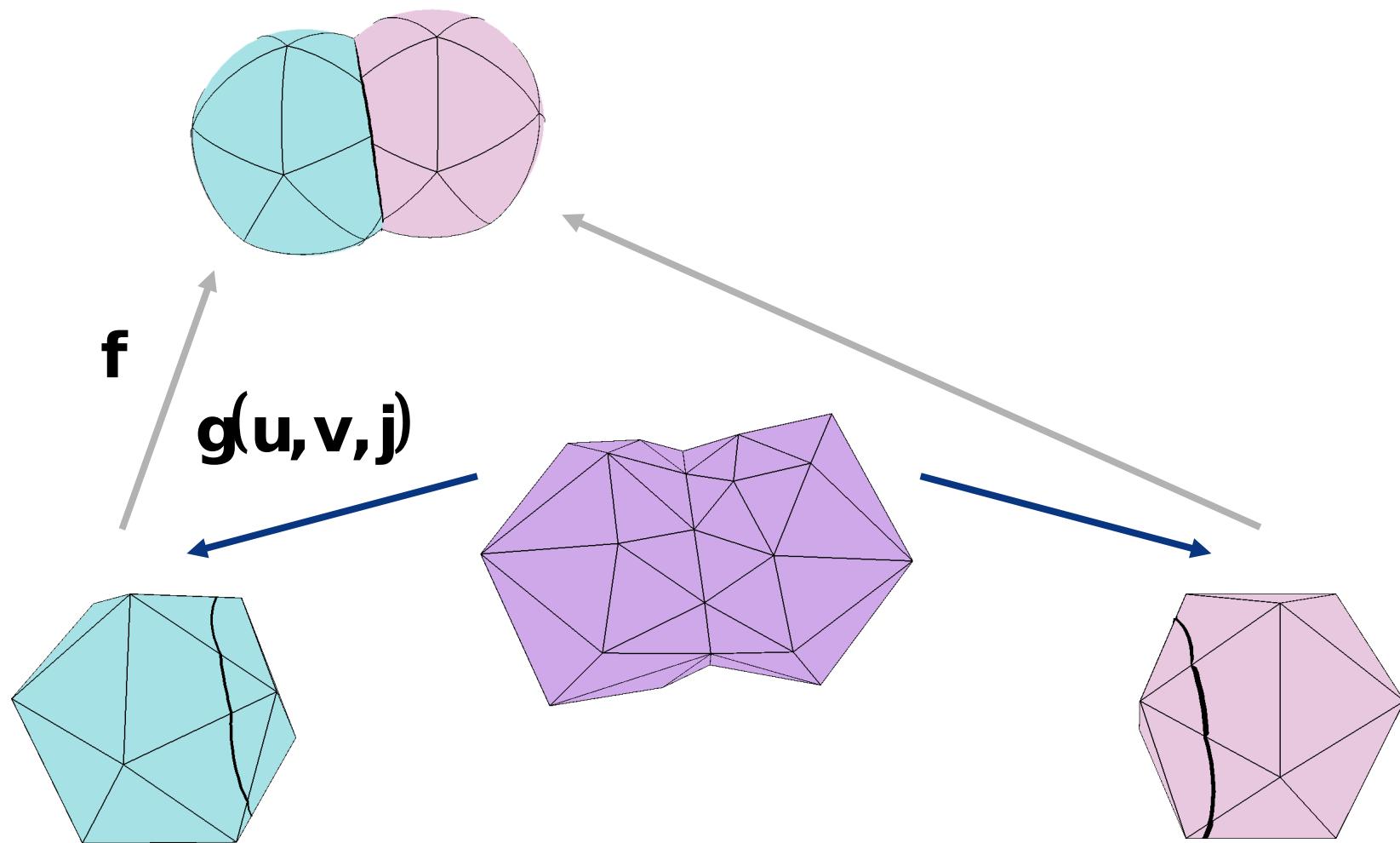
Topological Sphere



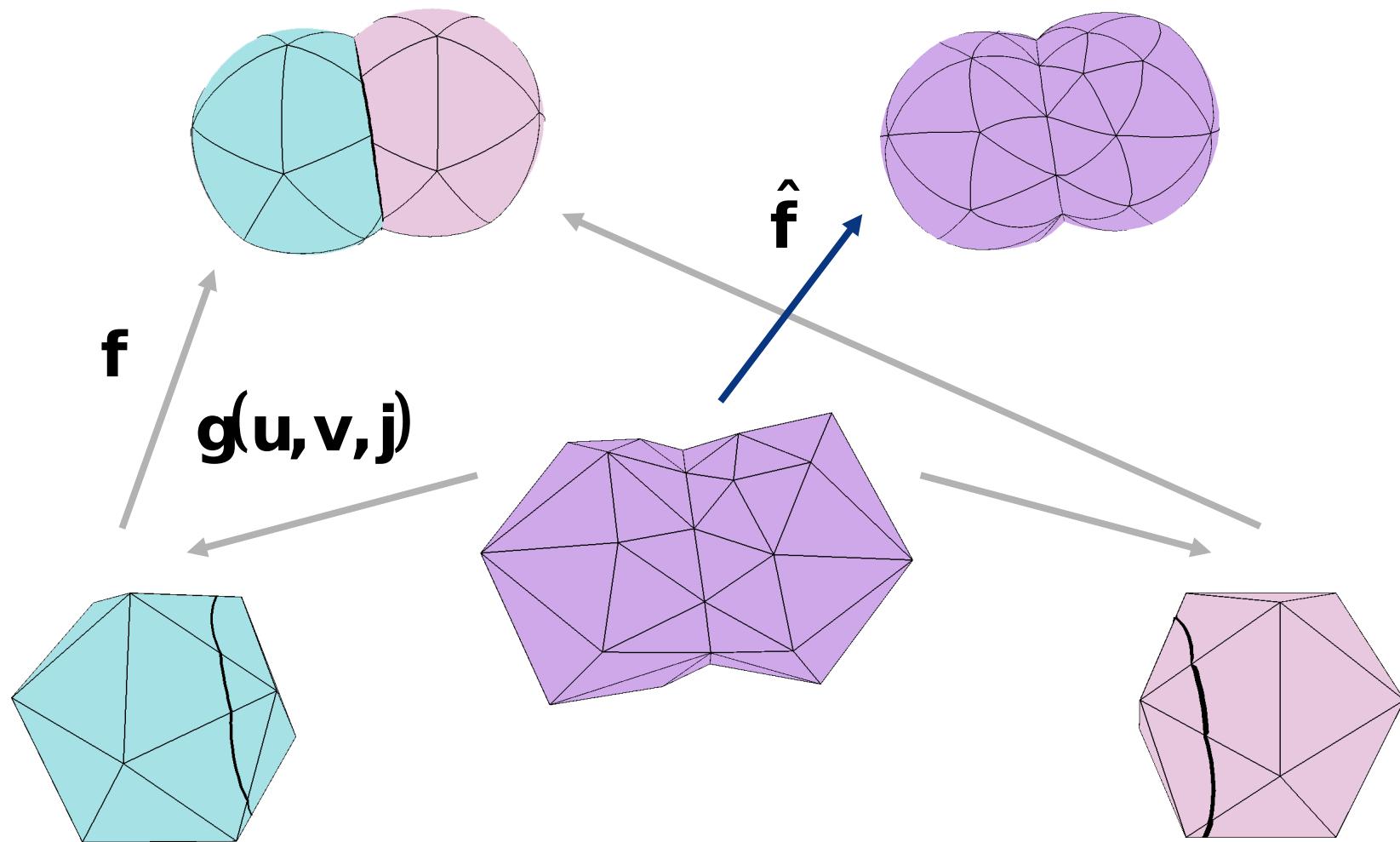
Fitting



Fitting

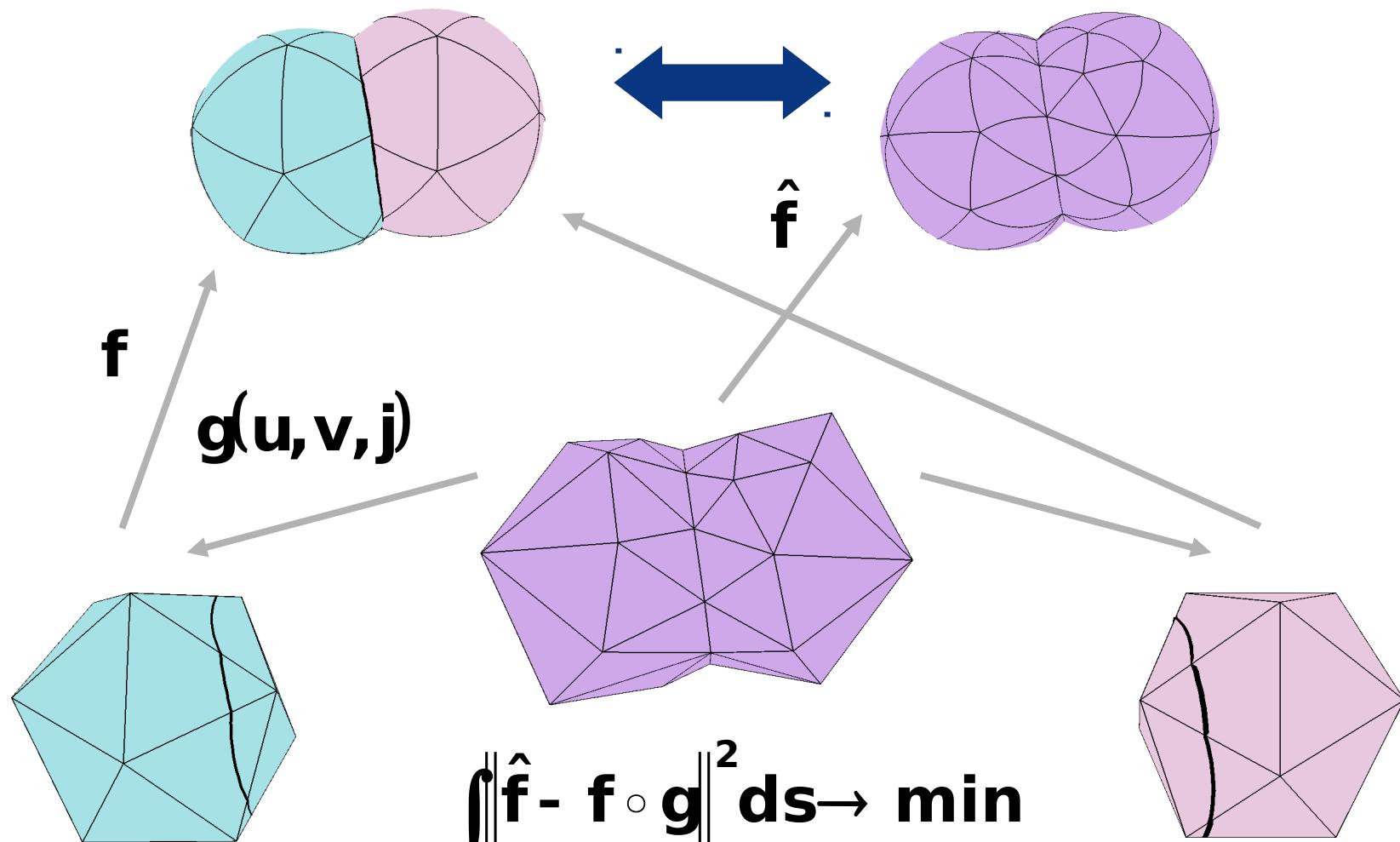


Fitting



Fitting

minimize difference



Fitting

- original surface \mathbf{f}
- new surface $\hat{\mathbf{f}}$
- parameterization \mathbf{g}
- minimize: $\int \|\hat{\mathbf{f}} - \mathbf{f} \circ \mathbf{g}\|^2 ds =$

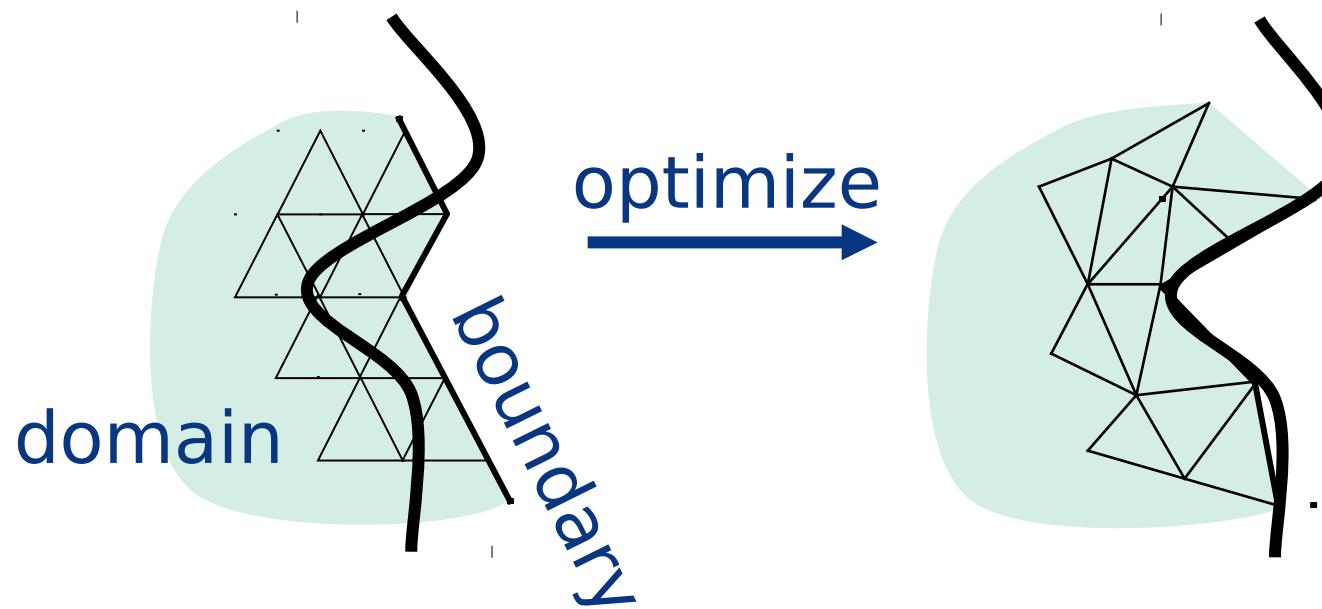
$$\int \left\| \sum_i p_i B_i(u, v, j) - \mathbf{f}(g(u, v, j)) \right\|^2 ds$$

control points

parameterization

Parameter optimization

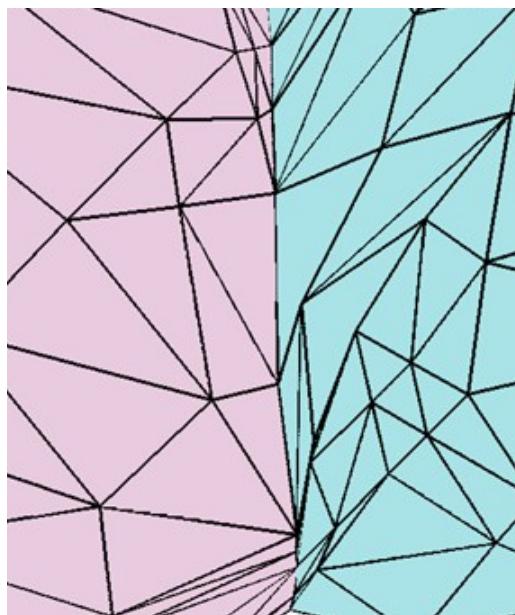
- mesh boundary not aligned with intersection curve
- idea: slide mesh along surface



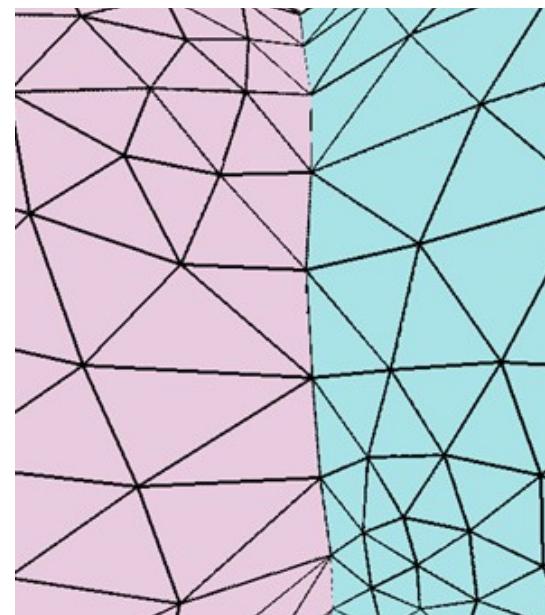
Parameter optimization

■ move vertices in domain

- optimize parameters
- goal: no folds, fair sampling

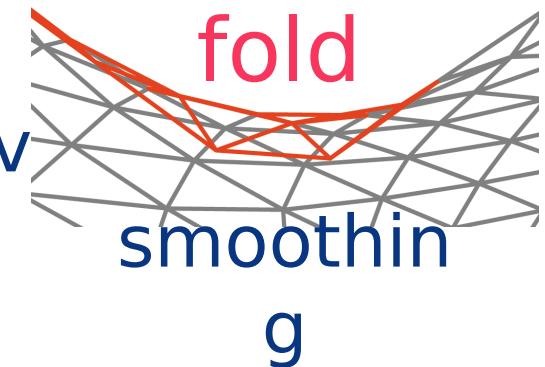


optimize
→

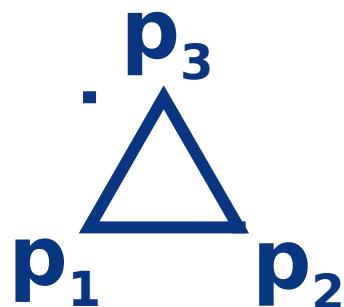


Parameter optimization

- Laplacian smoothing
fast, but folds at concav

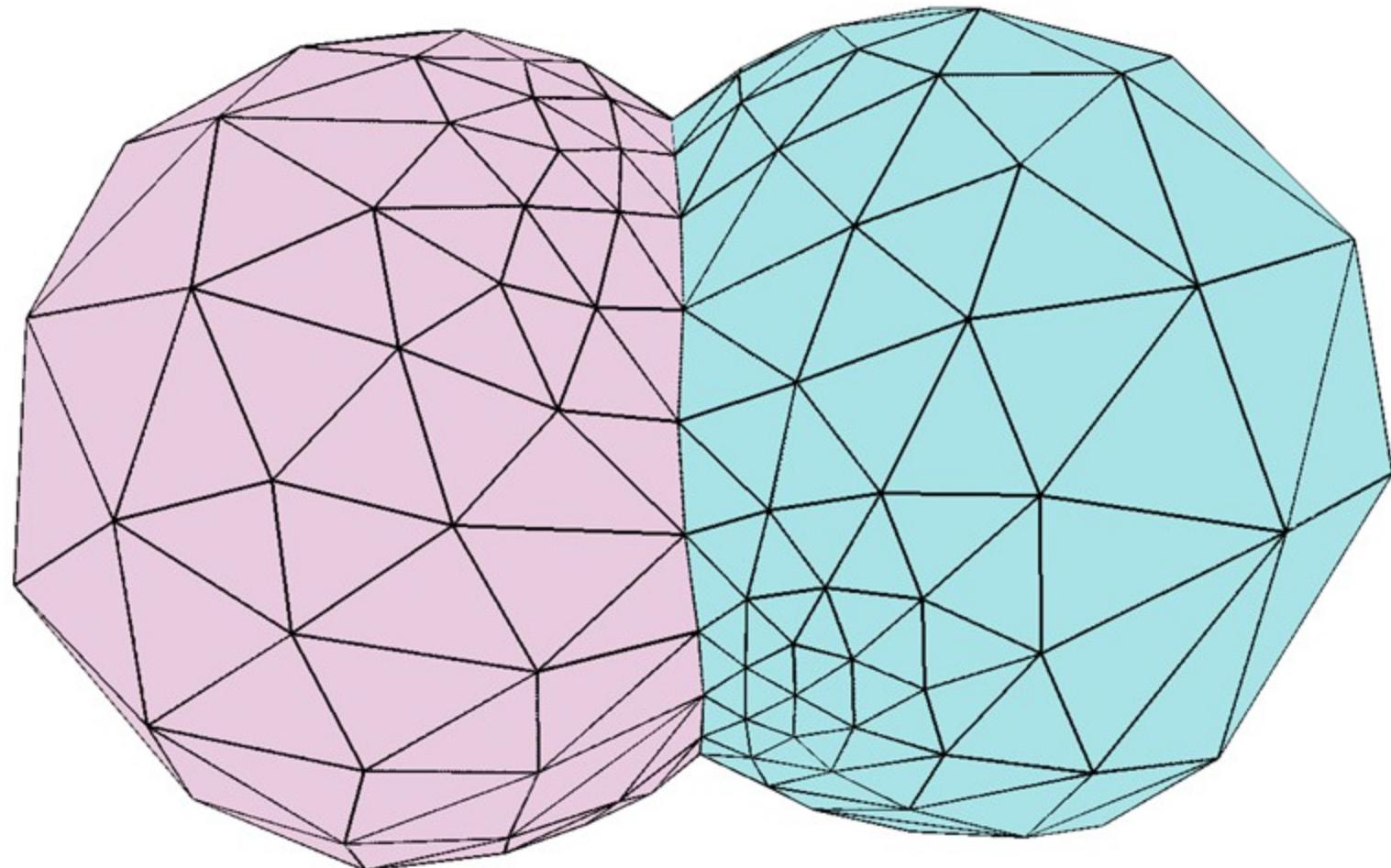


- area/perimeter optimization
penalize folds
improve aspect ratios



$$E_{123} = - \frac{\text{Area}(p_1 p_2 p_3)}{p_1^2 + p_2^2 + p_3^2}$$

Smooth domain



Optimize geometry

Control point positions

- least squares fit: sparse system

$$\int \left\| \sum_i p_i B_i(u, v, j) - f(g(u, v, j)) \right\|^2 ds$$

- better approximation

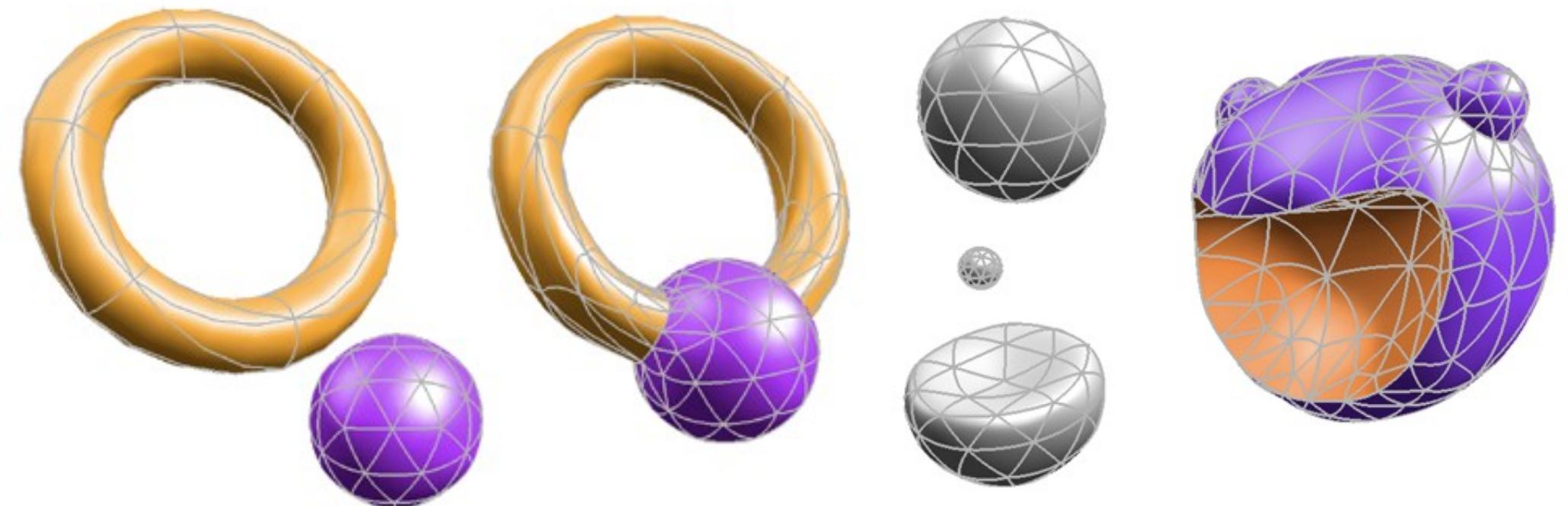
Hierarchical fitting

fitting p^{l+1}

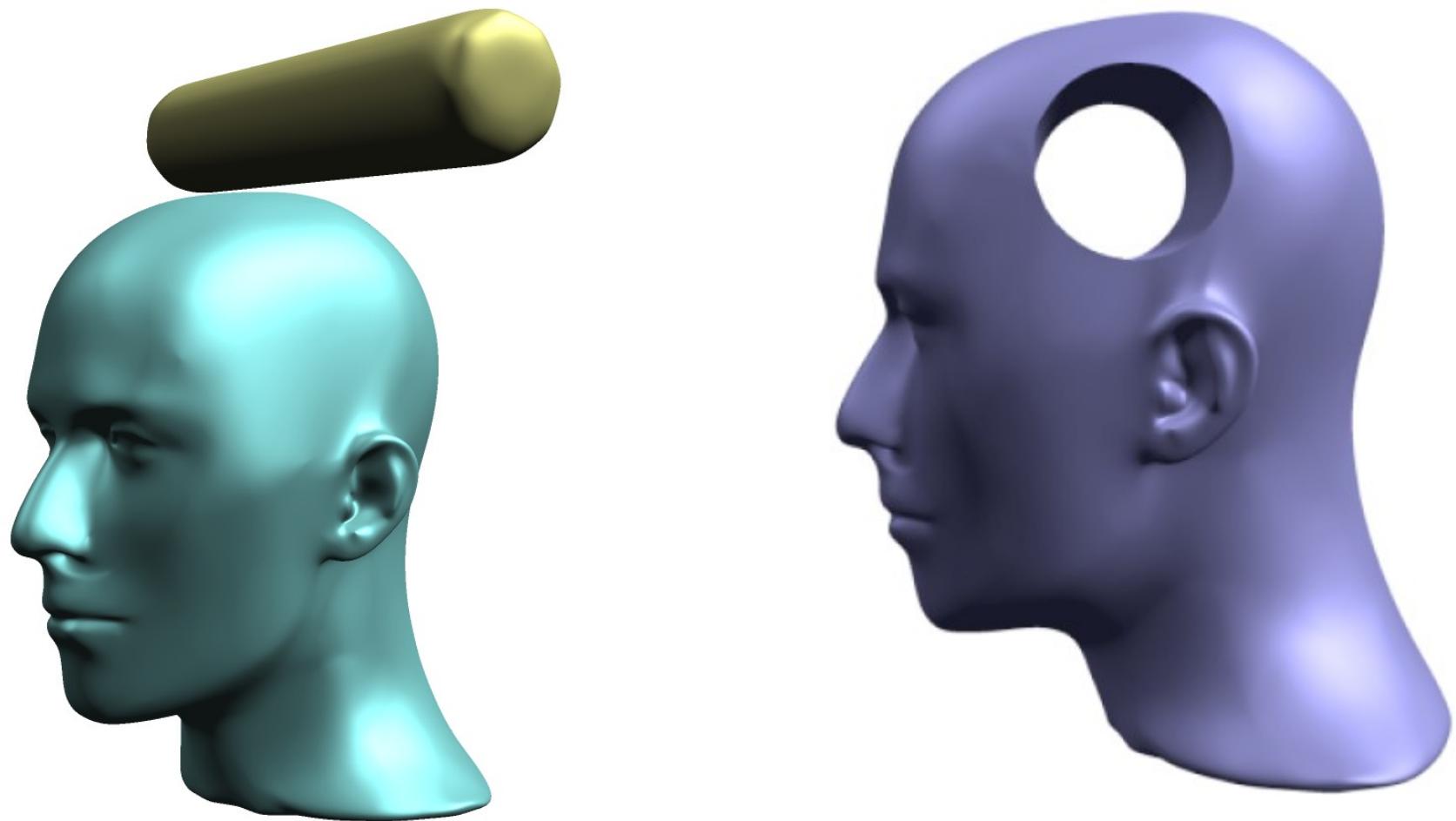
detail offset $d^{l+1} = p^{l+1} - S p^l$

Results

Small increase in the number
of patches in simple cases



Results



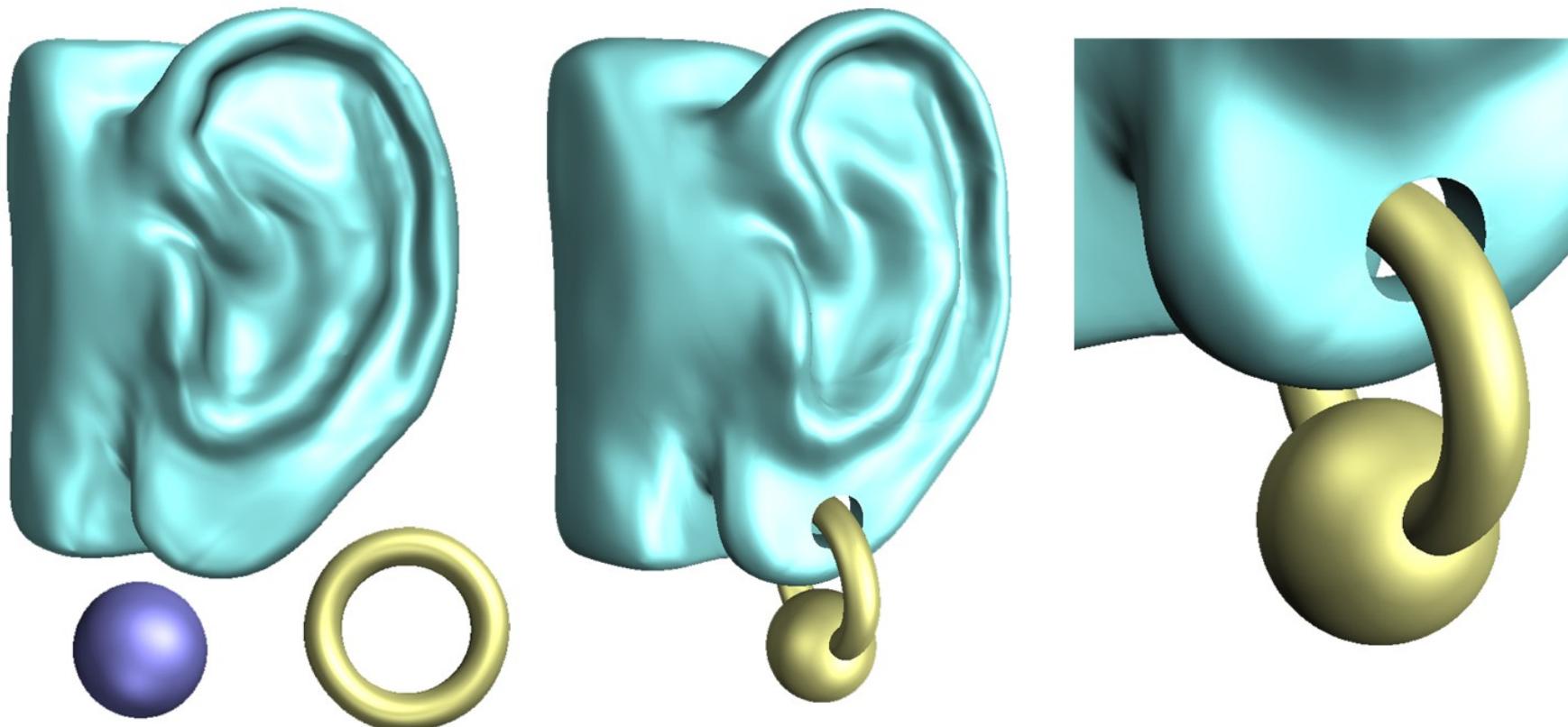
Results



Inspired by
S. Dalí's
Venus with
Drawers

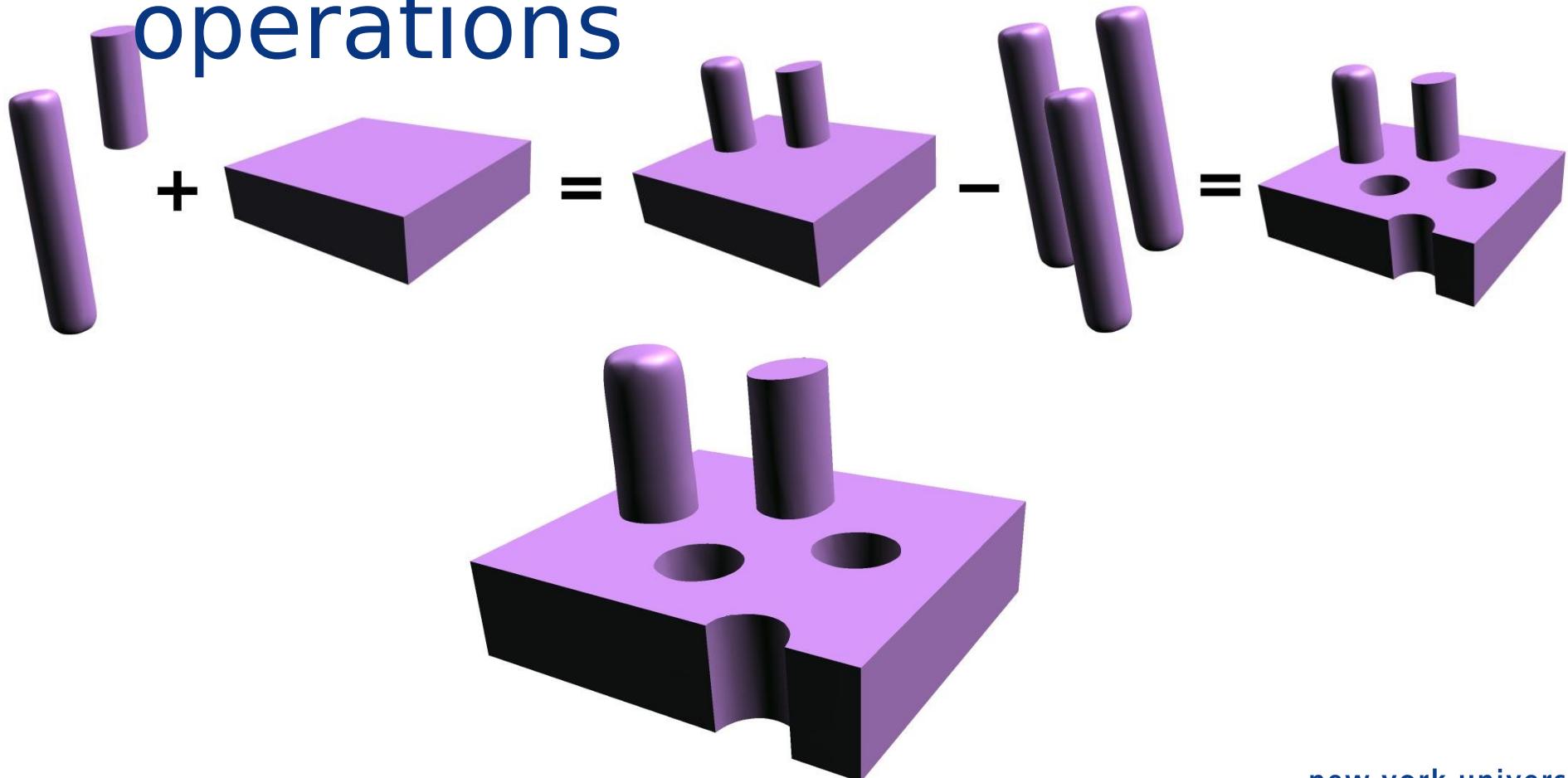
Results

Multires subdivision surfaces



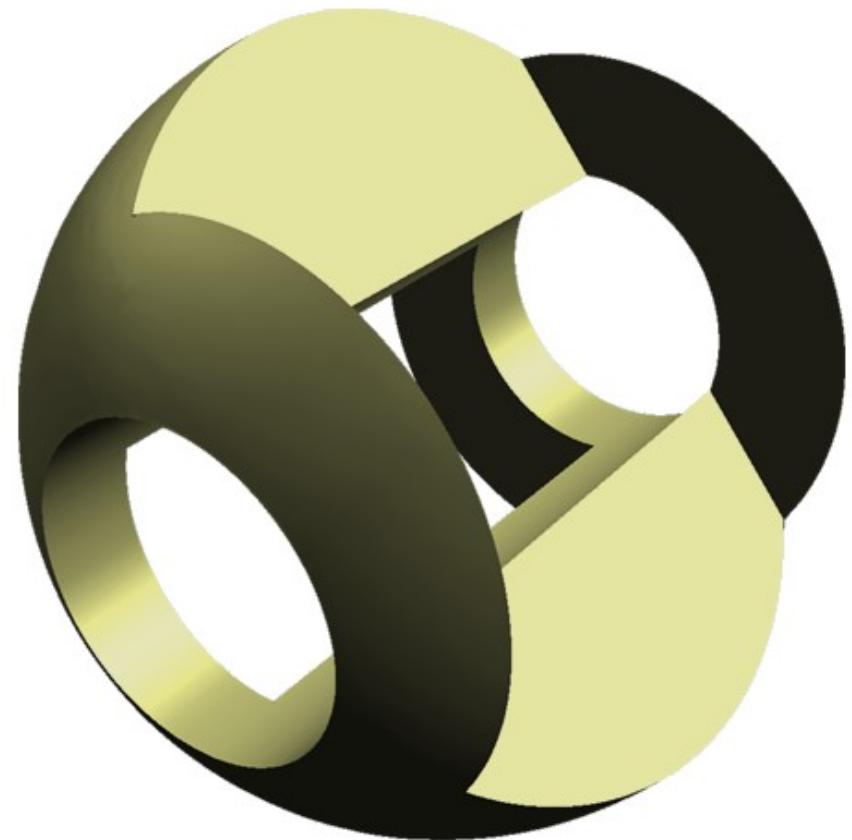
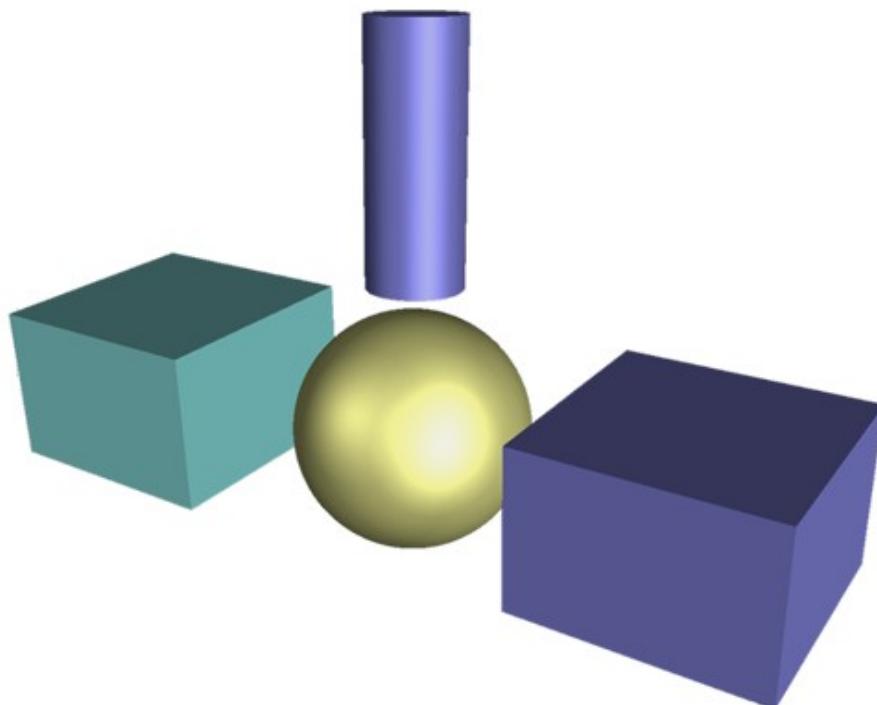
Results

Sequences of Boolean operations



Results

Piecewise-smooth solids



Conclusion

Contributions

- approximate Booleans
- graphics, design applications

Future work

- better parameterizations
- coarsening to get fewer patches
- approximation estimates
- combine with an accurate surface-surface intersection

